

Combinatorial certificates in SDP duality:
how elementary row operations help

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Parts joint work with Minghui Liu, Alex Touzov,

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A Semidefinite Program (SDP)

$$\inf_X C \bullet X$$

$$s.t. X \succeq 0$$

$$A_i \bullet X = b_i \quad (i = 1, \dots, m).$$

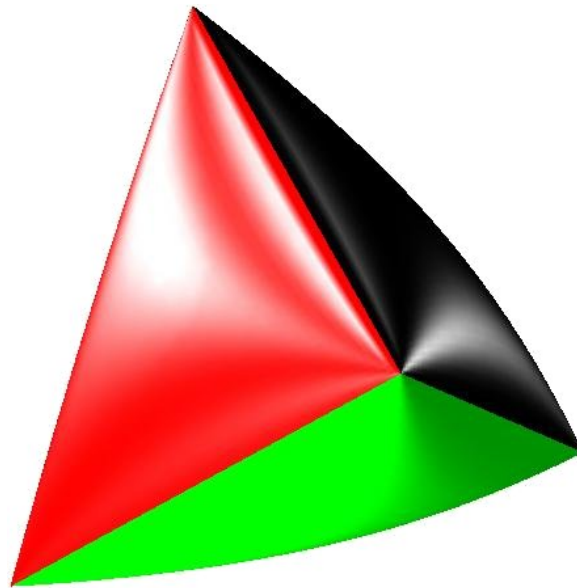
Here

- A_i, C are symmetric data matrices, X is variable matrix.
- For symmetric matrices $S, T : S \preceq T$ means: $T - S$ is positive semidefinite (psd).
- $S \bullet T = \sum_{i,j} s_{ij}t_{ij}$.
- $X \succeq 0 \stackrel{\text{def}}{\iff}$ all principal subdeterminants are nonnegative.
- Equivalently, if $v^T X v \geq 0 \forall v \in \mathbb{R}^n$.

Example: 3×3 correlation matrices: the elliptope

The set $\{X \succeq 0, \text{Diag}(X) = I_3\}$

can be represented as $\{(u, v, w) \mid \begin{pmatrix} 1 & u & v \\ u & 1 & w \\ v & w & 1 \end{pmatrix} \succeq 0\}$



Why is SDP important:
 $LP \subseteq SDP \subseteq \text{Convex Optimization}$

LP as SDP:

- If A_i and C are diagonal \Rightarrow we can assume so is X .
- And, diagonal matrix is psd \Leftrightarrow diagonal elements are non-negative.
- So LP can be modeled as SDP: make A_i, C diagonal.
- (Or: explicitly force offdiagonal elements of X to 0).

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SDP is a convex problem:

- Feasible set is convex, since set of psd matrices is.

Why is SDP important: applications in

- 0–1 Integer programming.
- Approx algorithms
- Chemical engineering
- Chemistry
- Coding theory
- Control theory
- Combinatorial opt
- Discrete geometry
- Eigenvalue optimization
- Facility planning
- Finance
- Geometric optimization
- Global optimization
- Graph visualization
- Inventory theory
- Machine learning
- Matrix analysis
- PDEs
- Probability theory
- Robust optimization
- Signal processing
- Statistics
- Structural optimization
- Several thousand (up to 20 thousand!) papers on SDP in the last 30 years.

Other "application"

- Gives good insight into convex optimization.
- Basics are just like in LP.
- **But:** What can go wrong in convex optimization already can go wrong in SDP.

Other "application"

- Gives good insight into convex optimization.
- Basics are just like in LP.
- **But:** What can go wrong in convex optimization already can go wrong in SDP.
- Precisely: to solve an SDP, we need:
 - A dual problem
 - An infeasibility certificate
- These are not quite the way we would like them to be.

SDP duality

$$\begin{array}{ll} \inf_X C \bullet X & \sup_y b^T y \\ (P) \quad s.t. \quad X \succeq 0 & \sum_{i=1}^m y_i A_i \preceq C \quad (D) \\ & A_i \bullet X = b_i \quad (i \in [m]). \end{array}$$

Easy: If X and y are feasible, then $C \bullet X \geq b^T y$.

But:

- unattained optimal values
- positive duality gaps
- Slater's condition helps, but it may not hold.
- SDP is poly time solvable only under restrictive assumptions

Alternative system (Farkas' lemma) to prove infeasibility

$$\inf_X C \bullet X$$

$$(P) \quad s.t. \quad X \succeq 0$$

$$A_i \bullet X = b_i \quad (i \in [m]).$$

$$\sum_{i=1}^m y_i A_i \succeq 0 \quad (ALT-P)$$

$$b^\top y = -1$$

Easy: (P) infeasible $\Leftrightarrow (ALT-P)$ feasible

But:

- \nRightarrow
- Thus $(ALT-P)$ is not useful for complexity
- not known whether feasibility of (P) can be decided in polynomial time

Some partial history of duality in conic linear programs:

- **Duffin, 1956:** Infinite programs
- **Berman, 1973:** Cones, matrices, and mathematical programming
- **Ben-Israel, Charnes, Kortanek, 1968:** Duality and asymptotic solvability over cones
- **Berman, Ben-Israel, 1971:** Duality and asymptotic solvability over cones
- **:**

Better understanding of in the last 15+ years
based on:

- (1) On the closedness of the linear image of a closed convex cone, P, 2007
- (2) Facial reduction: Borwein-Wolkowicz 80-81; Waki-Muramatsu 2012; P 2000, 2013, Liu-P 2016
- (3) Elementary row operations

Elementary row operations for linear systems:

$Ax = b$ is infeasible \Leftrightarrow by elementary row operations it can be transformed into

$$A'x = b'$$

$$0^T x = 1$$

- \Leftarrow is easy, so a good certificate
- Can be used to generate any infeasible system

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We will use these operations to understand SDPs:

Part 1 Badly behaved feasible SDPs

Part 2 Infeasible SDPs

Part 3 Asymptotic feasibility, weak infeasibility

Part 4 Ramana's perfect infeasibility certificate

Reformulations

$$\begin{array}{ll} \inf_X C \bullet X & \sup_y b^T y \\ (P) \quad s.t. \quad X \succeq 0 & \sum_{i=1}^m y_i A_i \preceq C \quad (D) \\ & A_i \bullet X = b_i \quad (i \in [m]). \end{array}$$

We obtain a reformulation of (P) – (D) by a sequence of the following:

- Elementary row operations on the equations of (P)
- For $\lambda \in \mathbb{R}^m$

$$C \leftarrow C + \sum_i \lambda_i A_i$$

- For a V invertible matrix

$$A_i \leftarrow V^T A_i V \quad (i \in [m]), \quad C \leftarrow V^T C V,$$

Part 1: Why all bad SDPs look the same

Dual :

$$\begin{aligned} \sup 2y_1 & \Leftrightarrow \sup 2y_1 \\ \text{s.t. } y_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} & \text{s.t. } \begin{pmatrix} 1 & -y_1 \\ -y_1 & 0 \end{pmatrix} \preceq 0 \end{aligned}$$

Only feasible y_1 is $y_1 = 0$.

Primal (with variable matrix X) is equivalent to:

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Primal (with variable matrix X) is equivalent to:

$$\begin{aligned} \inf x_{11} \\ \text{s.t. } x_{11} \geq 0, x_{22} \geq 0, x_{11}x_{22} \geq 1. \end{aligned}$$

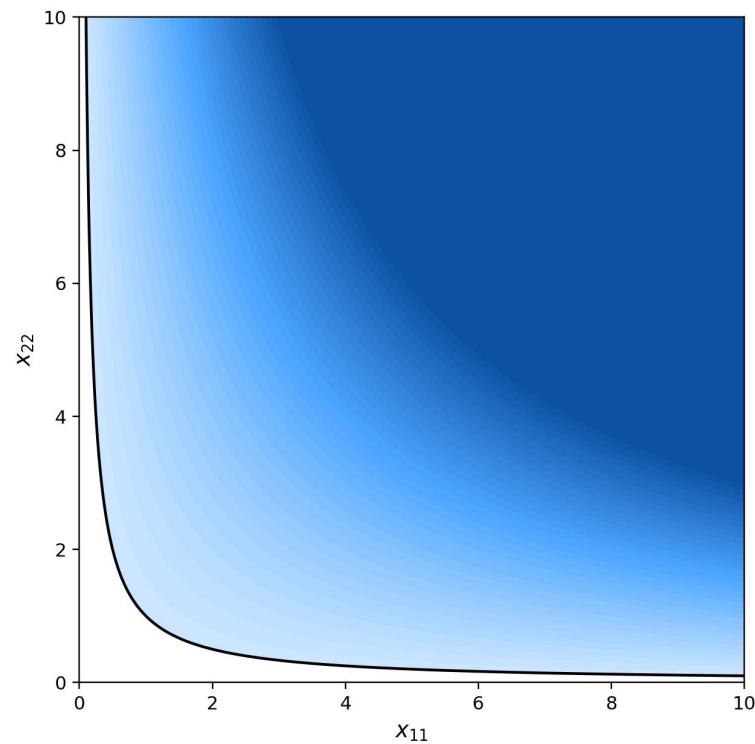
Part 1: Why all bad SDPs look the same

But

$$\inf x_{11}$$

$$s.t. \ x_{11} \geq 0, \ x_{22} \geq 0, \ x_{11}x_{22} \geq 1.$$

has unattained infimum!



Part 1: Why all bad SDPs look the same

- Semidefinite system:

$$(D_{sys}) \quad \sum_{i=1}^m y_i A_i \preceq C$$

We say (D_{sys}) is badly behaved, if $\exists b$ s.t.

$$\sup\{ b^\top y \mid y \in D_{sys} \}$$

is finite, but (P) has no solution with the same value.

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is finite, but (P) has no solution with the same value.

- A **slack matrix** in (D) is a matrix

$$Z := C - \sum_{i=1}^m y_i A_i \succeq 0.$$

Part 1: Why all bad SDPs look the same

One variable case: In

$$(D_{sys}) \quad y_1 \begin{pmatrix} \overbrace{V_{11}}^r & V_{12} \\ V_{12}^T & \underbrace{V_{22}}_{n-r} \end{pmatrix} \preceq \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix},$$

suppose rhs is the maximum rank slack. Then (D_{sys}) is badly behaved \Leftrightarrow

$$V_{22} \succeq 0, \quad R(V_{12}^T) \not\subseteq R(V_{22}).$$

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$$V_{22} \succeq 0, R(V_{12}^T) \not\subseteq R(V_{22}).$$

So, just a larger version of

$$y_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

Part 1: Why all bad SDPs look the same

Theorem: Assume in

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Then (D_{sys}) is badly behaved $\Leftrightarrow \exists$ reformulation

$$(D'_{sys}) \quad \sum_{i=1}^m y_i A'_i \preceq C$$

s.t.

$$y_1 A'_1 \preceq C$$

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is badly behaved.

I.e., one variable bad subsystem certifies bad behavior.

Part 1: Why all bad SDPs look the same

Example

$$y_1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + y_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

has positive gap, when we seek $\sup y_2$.

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One variable bad subsystem:

$$\cancel{y_1} \begin{pmatrix} \cancel{1} & \cancel{0} & \cancel{0} \\ \cancel{0} & \cancel{0} & \cancel{0} \\ \cancel{0} & \cancel{0} & \cancel{0} \end{pmatrix} + y_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Part 2: Infeasibility

Example

$$\underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}}_{A_1} \bullet X = \underbrace{0}_{b_1}$$
$$\underbrace{\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}}_{A_2} \bullet X = \underbrace{-1}_{b_2}$$
$$X \succeq 0$$

Farkas lemma certificate fails: there is no $y \in \mathbb{R}^2$ s.t.

$$y_1 A_1 + y_2 A_2 \succeq 0, \quad y_1 b_1 + y_2 b_2 = -1.$$

Part 2: Infeasibility

Example

$$\begin{array}{l} \left(\begin{array}{ccc} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right) \bullet X = 0 \\ \left(\begin{array}{ccc} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{array} \right) \bullet X = -1 \\ X \succeq 0 \end{array}$$

Still, it is easy to see why it is infeasible:

- Suppose X feasible $\Rightarrow x_{11} = 0$
 $\Rightarrow x_{12} = x_{13} = 0$
 $\Rightarrow x_{22} = -1$, contradiction!

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We will find such a structure in every infeasible semidefinite system.

Some linear algebra

$$\begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix} \bullet X = 0, X \succeq 0 \Rightarrow ?$$

Some linear algebra

$$\begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix} \bullet X = 0, X \succeq 0 \Rightarrow X = \begin{pmatrix} 0_r & 0 \\ 0 & X_{22} \end{pmatrix}, X_{22} \succeq 0.$$

Theorem: (P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}
 \quad (\mathbf{P}_{\text{ref, infeas}})$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times}^{n-r_1-\dots-r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_i \geq 0 \forall i$.

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with $r_i \geq 0 \forall i$. Liu-P, 2015

Proof of “ \Leftarrow ” : Suppose X feasible in $(P)_{\text{ref, infeas}}$

\Rightarrow first r_1 rows of X are 0

...

\Rightarrow first $r_1 + \dots + r_k$ rows of X are 0

\Rightarrow trace of diag. block of X is -1 , contradiction!

Proof of “ \Rightarrow ” : Also not hard P-Touzov, 2022

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A normal form of empty spectrahedra

Application 1: generating infeasible SDPs

By this theorem, we can generate **any** infeasible SDP, as:

- (1) Generate a system like (P_{ref})
- (2) Reformulate it.

There are only finitely many representative infeasible SDPs!

How many? # of partitions of $\{1, \dots, n\}$ into nonempty subsets

Problem library by **Liu-P** 2016: infeasible SDPs

Application 2: better understanding of polynomial optimization

Example: Motzkin polynomial

$$f(x, y) = 1 - 3x^2y^2 + x^2y^4 + x^4y^2$$

It is ≥ 0

To certify nonnegativity, we can try to find a sum of squares (SOS) decomposition $f = \sum_i (f_i)^2$ for some f_i polynomials.

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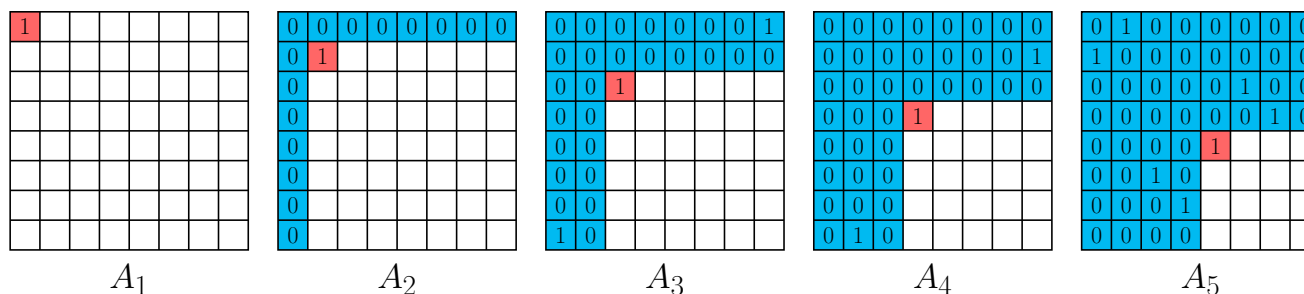
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Checking SOSness is an SDP (Lasserre, Parrilo)

f is **not** SOS \Rightarrow The SDP is infeasible, and in the form of $(P_{\text{ref, infeas}})$ without any reformulation

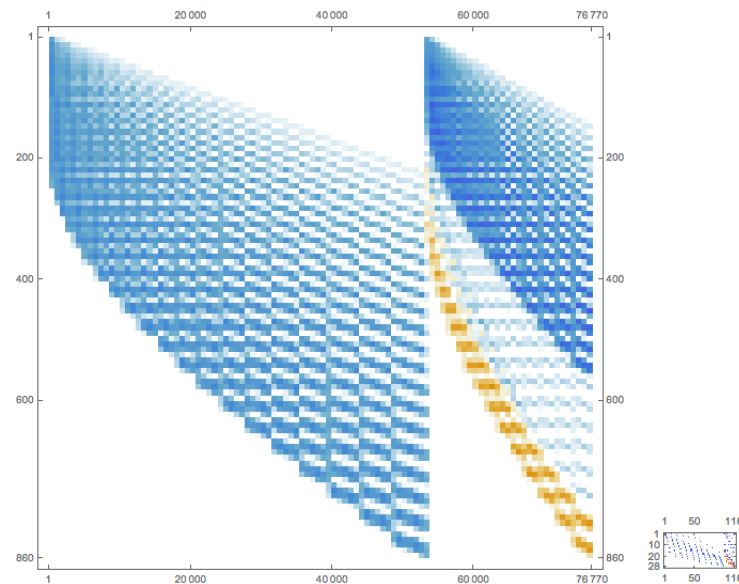


with $(b_1, b_2, b_3, b_4, b_5) = (0, 0, 0, 0, -3)$

Paper: P-Touzov, 2022, FOCM

Application 3: recognizing infeasibility in practice

- Sometimes we do not even have to reformulate an SDP to find the trivial structure that proves infeasibility ...or to reduce the SDP.
- **Zhu–P–Tran-Dinh, 2018** Fast Sieve-SDP preprocessor
- Before and after picture of an SDP



Though this is a best case example, many polynomial optimization problems get greatly reduced.

Part 3: Asymptotic feasibility, weak infeasibility

- Recall dual, without objective function:

$$(D) \quad \sum_{i=1}^m y_i A_i \preceq C$$

- We say (D) is asymptotically feasible, if an arbitrarily small perturbation of C makes it feasible.
- Feasible \Rightarrow asymptotically feasible. But: \nRightarrow

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- Feasible \Rightarrow asymptotically feasible. But: \nRightarrow
- We say (D) is weakly infeasible, if infeasible, but asymptotically feasible.
- Weakly infeasible SDPs are hard: often mistaken for feasible ones by solvers

Part 3: Asymptotic feasibility, weak infeasibility

Example:

$$y_1 \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}}_{A_1} + y_2 \underbrace{\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix}}_{A_2} \not\leq \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}}_C$$

is weakly infeasible.

Infeasible:

$$S := C - y_1 A_1 - y_2 A_2 = \begin{pmatrix} -y_1 & 0 & -y_2 \\ 0 & -y_2 & 1 \\ -y_2 & 1 & 0 \end{pmatrix} \not\leq 0$$

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Asymptotically feasible: for any $\epsilon > 0$

$$S_\epsilon := C - y_1 A_1 - y_2 A_2 = \begin{pmatrix} -y_1 & 0 & -y_2 \\ 0 & -y_2 & 1 \\ -y_2 & 1 & \epsilon \end{pmatrix} \succ 0 :$$

choose y_2 to make lower right 2×2 block $\succ 0$; then choose y_1 to make $S_\epsilon \succ 0$.

Theorem: (D) asymptotically feasible \Leftrightarrow it has a reformulation

$$\sum_{i=1}^m y_i A'_i \preceq C'$$

where $0 \leq \ell \leq m$ and for $i = 1, \dots, \ell$

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ \mathbf{0} & \mathbf{0} \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times}^{n-r_1-\dots-r_i} \\ \times & I & \mathbf{0} \\ \times & \mathbf{0} & \mathbf{0} \end{pmatrix},$$

and

$$C' = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_\ell} & \overbrace{\times}^{r_{\ell+1}} & \overbrace{\times}^{n-r_1-\dots-r_{\ell+1}} \\ \times & I & \mathbf{0} \\ \times & \mathbf{0} & \mathbf{0} \end{pmatrix}$$

with $r_i \geq 0 \forall i$.

Lourenco-Muramatsu-Tsuchiya, 2014 essentially same statement, Liu-P, 2017 stated in terms of reformulations, and short proof

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with $r_i \geq 0 \forall i$.

Proof of “ \Leftarrow ”: Just like in special case

Proof of “ \Rightarrow ”: (D) asymptotically feasible \Leftrightarrow its Farkas' lemma system

$$A_i \bullet X = 0 \forall i, \quad C \bullet X = -1, \quad X \succeq 0$$

is infeasible. + Reformulate this system.

Part 3: Asymptotic feasibility, weak infeasibility

- We can define asymptotic feasibility, weak infeasibility of (P) similarly.
- Combining certificates for infeasibility and asymptotic feasibility \rightarrow generating algorithm for **all** weakly infeasible SDPs.
P, Touzov 2022

Part 4: Ramana's alternative system

Ramana, 1995: A perfect dual for (P) or (D) : no duality gap, always attains optimal value

Gives an exact alternative system for (D) and best complexity results to date.

I will talk about the alternative system for (P) .

Part 4: Ramana's alternative system

Motivation: LP infeasibility

$$\begin{array}{ll} (P) & Ax = b \\ & x \geq 0 \end{array} \qquad \begin{array}{ll} & A^T y \geq 0 \\ & b^T y = -1 \end{array} \quad (ALT-P)$$

Three desirable properties:

- (1) Data of (P) is same as that of $(ALT-P)$? **YES**
- (2) (P) is infeasible $\Leftrightarrow (ALT-P)$ is feasible? **YES**
- (3) When feasible, they have poly size solutions ? **YES**

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- (3) When feasible, they have poly size solutions ? **YES**

Corollary: LP feasibility $\in \mathbf{NP} \cap \mathbf{co-NP}$ in both Turing and real number model. Known already in the sixties.

Part 4: Ramana's alternative system

Now to SDP

$$\mathcal{A}X := (A_1 \bullet X, \dots, A_m \bullet X)^\top, \quad \mathcal{A}^*y := \sum_{i=1}^m y_i A_i$$

$$\begin{array}{ll} (P) & \mathcal{A}X = b \\ & X \succeq 0 \end{array} \qquad \begin{array}{ll} & \mathcal{A}^*y \succeq 0 \\ & b^T y = -1 \end{array} \quad (ALT-P)$$

$(ALT-P)$ is traditional alternative system

Three desirable properties:

- (1) Data of (P) is same as that of $(ALT-P)$? **YES**
- (2) (P) is infeasible $\Leftrightarrow (ALT-P)$ is feasible? **NO: \Rightarrow may fail.**
- (3) When feasible, they have poly size solutions ? **NO**

Part 4: Ramana's alternative system

Now to SDP

$$\mathcal{A}X := (A_1 \bullet X, \dots, A_m \bullet X)^\top, \quad \mathcal{A}^*y := \sum_{i=1}^m y_i A_i$$

$$\begin{array}{ll} (P) & \mathcal{A}X = b \\ & X \succeq 0 \end{array} \qquad \begin{array}{ll} & \mathcal{A}^*y \succeq 0 \\ & b^T y = -1 \end{array} \quad (ALT-P)$$

$(ALT-P)$ is traditional alternative system

Three desirable properties:

- (1) Data of (P) is same as that of $(ALT-P)$? **YES**
- (2) (P) is infeasible $\Leftrightarrow (ALT-P)$ is feasible? **NO**
- (3) When feasible, they have poly size solutions ? **NO**

Corollary: $(ALT-P)$ is not useful for complexity

Part 4: Ramana's alternative system (Ram-Alt-P)

Three desirable properties:

- (1) Data of (P) is same as that of (Ram-Alt-P) ? **YES**
- (2) (P) is infeasible \Leftrightarrow (Ram-Alt-P) is feasible? **YES**
- (3) When feasible, they have poly size solutions ? **NO**

Part 4: Ramana's alternative system (Ram-Alt-P)

Three desirable properties:

- (1) Data of (P) is same as that of (Ram-Alt-P) ? YES
- (2) (P) is infeasible \Leftrightarrow (Ram-Alt-P) is feasible? YES
- (3) When feasible, they have poly size solutions ? NO

Corollary: SDP feasibility

- $\in \text{NP} \cap \text{co-NP}$ in real number model.
- is not NP complete in Turing model, unless $\text{NP} = \text{co-NP}$
- After 30 years, still the best result we have.
- Very popular in computer science community.

Ramana's alternative system (Ram-Alt-P)

(P) is infeasible $\Leftrightarrow \exists 0 \leq k \leq n - 1 :$

$$\begin{array}{l}
 U_0 = V_0 = 0 \\
 \left. \begin{array}{l}
 \mathcal{A}^* y^i = U_i + V_i \\
 b^T y^i = 0 \\
 U_i \in \mathbb{S}_+^n \\
 V_i \in \tan(U_{i-1})
 \end{array} \right\} \text{for } i \in [k] \\
 \left. \begin{array}{l}
 \mathcal{A}^* y \in \mathbb{S}_+^n + \tan(U_k) \\
 b^T y = -1
 \end{array} \right\} \text{Like (Alt-P)}
 \end{array}$$

is feasible.

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$$\left. \begin{array}{l}
 \mathcal{A}^* y \in \mathbb{S}_+^n + \tan(U_k) \\
 b^T y = -1
 \end{array} \right\} \text{Like (Alt-P)}$$

is feasible.

- $\tan(U) = \tan(U, \mathbb{S}_+^n) = \left\{ V \in \mathbb{S}^n : \text{dist}(U \pm \epsilon V, \mathbb{S}_+^n) = o(\epsilon) \right\}$
- $\tan(U)$ is tangent space of \mathbb{S}_+^n at U .

E.g. $\tan \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \ni \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$, since $\begin{pmatrix} 1 & \epsilon \\ \epsilon & \epsilon^2 \end{pmatrix} \succeq 0$.

Ramana's alternative system (Ram-Alt-P)

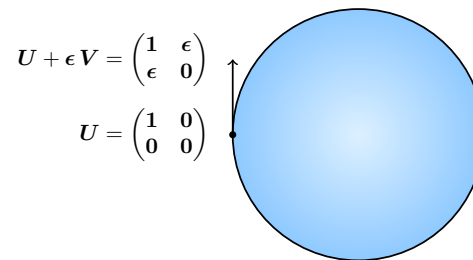
(P) is infeasible $\Leftrightarrow \exists 0 \leq k \leq n - 1 :$

$$U_0 = V_0 = 0$$

$$\left. \begin{aligned} \mathcal{A}^* y^i &= U_i + V_i \\ b^T y^i &= 0 \\ U_i &\in \mathbb{S}_+^n \\ V_i &\in \tan(U_{i-1}) \end{aligned} \right\} \text{for } i \in [k]$$

$$\left. \begin{aligned} \mathcal{A}^* y &\in \mathbb{S}_+^n + \tan(U_k) \\ b^T y &= -1 \end{aligned} \right\} \text{Like (Alt-P)}$$

is feasible.



The tangent space

Ramana's alternative system (Ram-Alt-P)

(P) is infeasible $\Leftrightarrow \exists 0 \leq k \leq n - 1 :$

$$\begin{array}{l}
 U_0 = V_0 = 0 \\
 \left. \begin{array}{l}
 \mathcal{A}^* y^i = U_i + V_i \\
 b^T y^i = 0 \\
 U_i \in \mathbb{S}_+^n \\
 V_i \in \tan(U_{i-1})
 \end{array} \right\} \text{for } i \in [k] \\
 \left. \begin{array}{l}
 \mathcal{A}^* y \in \mathbb{S}_+^n + \tan(U_k) \\
 b^T y = -1
 \end{array} \right\} \text{Like (Alt-P)}
 \end{array}$$

is feasible.

- Naturally, at least as strong as classical alternative (Alt-P) since $0 \in \tan(U) \forall U \succeq 0$

Ramana's alternative system (Ram-Alt-P)

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$$\begin{array}{l}
 U_0 = V_0 = 0 \\
 \left. \begin{array}{l}
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 \left. \begin{array}{l}
 \mathcal{A}^* y \in \mathbb{S}_+^n + \tan(U_k) \\
 b^T y = -1
 \end{array} \right\} \text{Like (Alt-P)}
 \end{array}$$

is feasible.

- $\tan(U)$ is representable by SDP:

- $\tan(U) = \left\{ W + W^T : \begin{pmatrix} U & W \\ W^T & \lambda I \end{pmatrix} \succeq 0 \exists \lambda \geq 0 \right\}.$

Ramana's alternative system (Ram-Alt-P)

(P) is infeasible $\Leftrightarrow \exists 0 \leq k \leq n - 1 :$

$$\begin{array}{l}
 U_0 = V_0 = 0 \\
 \left. \begin{array}{l}
 \mathcal{A}^* y^i = U_i + V_i \\
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 \mathcal{A}^* y \in \mathbb{S}_+^n + \tan(U_k) \\
 b^T y = -1
 \end{array} \right\} \text{Like (Alt-P)}
 \end{array}$$

is feasible.

- In words: in (Ram-Alt-P) we decompose each $\mathcal{A}^* y^i$ and $\mathcal{A}^* y$ into a psd part and a tangent space part.
- \Leftarrow is easy
- \Rightarrow is hard.
- We show: proof of \Rightarrow naturally fits into reformulation framework.

Proof sketch of \Rightarrow :

$$U_0 = V_0 = 0$$

$$\left. \begin{aligned} \mathcal{A}^* y_i &= U_i + V_i \\ b^T y_i &= 0 \\ U_i &\in \mathbb{S}_+^n \\ V_i &\in \tan(U_{i-1}) \end{aligned} \right\} \text{for } i \in [k]$$

$$\left. \begin{aligned} \mathcal{A}^* y &\in \mathbb{S}_+^n + \tan(U_k) \\ b^T y &= -1 \end{aligned} \right\} \text{Like (Alt-P)}$$

Key observation: **(Ram-Alt-P)** invariant under reformulating **(P)**. (E.g. rotations preserve tangent space)

So we assume infeasible **(P)** was reformulated into **($P_{\text{ref, infeas}}$)**.

Proof sketch of \Rightarrow :

$$\left. \begin{aligned} U_0 = V_0 = 0 \\ \mathcal{A}^* y_i = U_i + V_i \\ b^T y_i = 0 \\ U_i \in \mathbb{S}_+^n \\ V_i \in \tan(U_{i-1}) \end{aligned} \right\} \text{for } i \in [k]$$
$$\left. \begin{aligned} \mathcal{A}^* y \in \mathbb{S}_+^n + \tan(U_k) \\ b^T y = -1 \end{aligned} \right\} \text{Like (Alt-P)}$$

Key observation: **(Ram-Alt-P)** invariant under reformulating **(P)**. (E.g. rotations preserve tangent space)

So we assume infeasible **(P)** was reformulated into **($P_{\text{ref, infeas}}$)**.

Sketch of proof sketch: incremental structure in both **(Ram-Alt-P)** and **($P_{\text{ref, infeas}}$)**.

\rightarrow We will prove: $y_1 := e_1, \dots, y_k := e_k, y := e_{k+1}$ feasible in **(Ram-Alt-P)**

Useful fact about tangent spaces

$$\tan \begin{pmatrix} I & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} \times & \times \\ \times & 0 \end{pmatrix}$$

E.g.

$$\tan \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \ni \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Proof of (P) infeasible \Rightarrow (Ram - Alt - P) is feasible

$$\underbrace{\begin{pmatrix} I_{r_1} & 0 \\ 0 & 0 \end{pmatrix}}_{A_1} \bullet X = 0 \\
 \underbrace{\begin{pmatrix} \times_{r_1} & \times & \times \\ \times & I_{r_2} & 0 \\ \times & 0 & 0 \end{pmatrix}}_{A_2} \bullet X = 0 \\
 \vdots \quad (P_{\text{ref, infeas}}) \\
 \underbrace{\begin{pmatrix} \times_{r_1+\dots+r_k} & \times & \times \\ \times & I_{r_{k+1}} & 0 \\ \times & 0 & 0 \end{pmatrix}}_{A_{k+1}} \bullet X = -1 \\
 \vdots \\
 X \succeq 0$$

Matrices naturally decompose

$$\underbrace{\begin{pmatrix} I_{r_1} & 0 \\ 0 & 0 \end{pmatrix}}_{A_1=U_1 \succeq 0}$$

$$\underbrace{\begin{pmatrix} \times_{r_1} & \times & \times \\ \times & I_{r_2} & 0 \\ \times & 0 & 0 \end{pmatrix}}_{A_2} = \underbrace{\begin{pmatrix} I_{r_1} & 0 & 0 \\ 0 & I_{r_2} & 0 \\ 0 & 0 & 0 \end{pmatrix}}_{U_2 \succeq 0} + \underbrace{\begin{pmatrix} \times_{r_1} & \times & \times \\ \times & 0 & 0 \\ \times & 0 & 0 \end{pmatrix}}_{V_2 \in \tan(U_1)}$$

$$\underbrace{\begin{pmatrix} \times_{r_1+r_2} & \times & \times \\ \times & I_{r_3} & 0 \\ \times & 0 & 0 \end{pmatrix}}_{A_3} = \underbrace{\begin{pmatrix} I_{r_1+r_2} & 0 & 0 \\ 0 & I_{r_3} & 0 \\ 0 & 0 & 0 \end{pmatrix}}_{U_3 \succeq 0} + \underbrace{\begin{pmatrix} \times_{r_1+r_2} & \times & \times \\ \times & 0 & 0 \\ \times & 0 & 0 \end{pmatrix}}_{V_3 \in \tan(U_2)} \dots$$

$\Rightarrow y_1 := e_1, \dots, y_k := e_k, y := e_{k+1}$ feasible in (Ram-Alt-P)

Machinery used

- At start: subdifferentials, relative interiors, faces, conjugate faces, gauge functions, quadratic modules . . .
- More recently, only 2 ingredients:
 - Strong duality under Slater condition
 - Basic linear algebra
- Analogy with LP: in LP we need strong duality+ basic linear algebra.

Papers

- **P**: Bad semidefinite programs: they all look the same, **2010–SIOPT 2017**
- **Liu–P**: Exact duality in semidefinite programming based on elementary reformulations, **SIOPT 2015**
- **Liu–P**: Exact duals and short certificates of infeasibility and weak infeasibility in conic linear programming, **MPA 2017**.
- **P**: Characterizing bad semidefinite programs: normal forms and short proofs, **SIREV 2017**
- **Zhu–P–Tran-Dinh**: Sieve-SDP: a simple facial reduction algorithm to preprocess semidefinite programs, **MPC, 2018**
- **Lourenco-Muramatsu-Tsuchiya**: A structural geometrical analysis of weakly infeasible SDPs, **J. Oper. Res. Soc. Jpn, 2016**
- **Permenter-Parrilo**: Partial facial reduction: simplified, equivalent SDPs via approximations of the PSD cone, **MPA, 2017**
- **Permenter-Friberg-Andersen**: Solving conic optimization problems via self-dual embedding and facial reduction **SIOPT 2017**
- **P**: A Combinatorial Approach to Ramana’s Exact Dual for Semidefinite Programming, **2024**

On Ramana's dual

- **Ramana, Tuncel, Wolkowicz, 1997, P 2000** other correctness proof, connection to FR
- **de Klerk, Terlaky, Roos 2000** Use of Ramana's dual in self-dual embeddings.
- **P 2013** again, connection to FR, and generalization to conic LPs over **nice cones**
- **Klep, Schweighofer 2013** exact dual, with analogous properties, based on algebraic geometry
- **Liu-P 2017** Ramana dual for arbitrary conic LPs
- **Lourenço-P 2022** One more correctness proof

Thank you!