

**Combinatorial Characterizations in Semidefinite
Programming Duality:
how Elementary Row Operations Help**

Gábor Pataki

Department of Statistics and Operations Research

UNC Chapel Hill

Talk at the CAM Colloquium

University of Chicago, October 2019

A Semidefinite Program (SDP)

$$\begin{aligned} \sup_x \quad & c^T x \\ \text{s.t.} \quad & \sum_{i=1}^m x_i A_i \preceq B. \end{aligned} \quad (SDP)$$

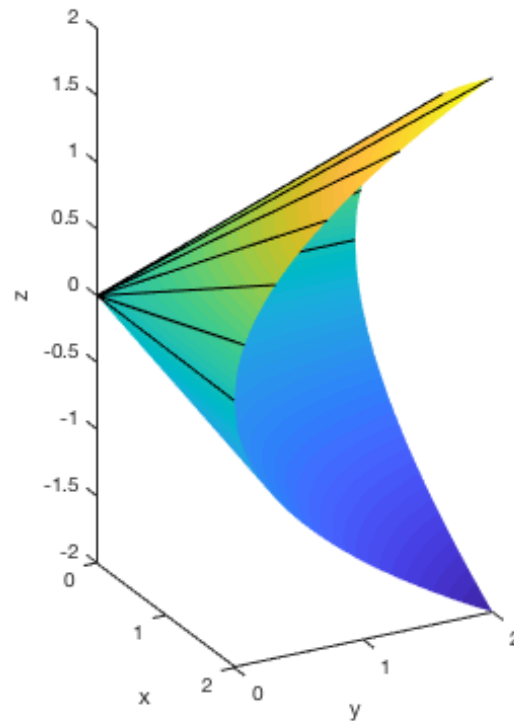
Here

- A_i, B are symmetric matrices, $c, x \in \mathbb{R}^m$.
- $A \preceq B$ means that $B - A$ is symmetric positive semidefinite (psd).
- An $n \times n$ matrix Y is positive semidefinite, if all principal subdeterminants are nonnegative.
- Equivalently, if $v^T Y v \geq 0 \forall v \in \mathbb{R}^n$.

Some nice pictures of SDP feasible sets, 1

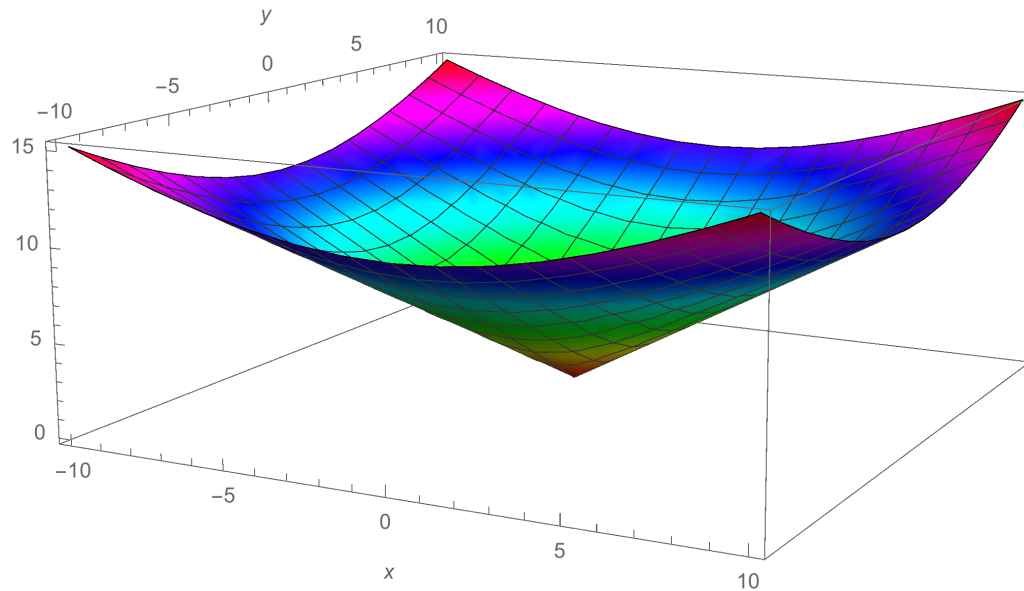
Picture of 2×2 psd cone:

$$\left\{ (x, y, z) : \begin{pmatrix} x & z \\ z & y \end{pmatrix} \succeq 0 \right\}$$



Some nice pictures of SDP feasible sets, 2

$$\left\{ (x, y, z) : zI \succeq \begin{pmatrix} x+1 & -y \\ -y & -x+1 \end{pmatrix} \right\}$$



Why is SDP important:
 $LP \subseteq SDP \subseteq \text{Convex Optimization}$

LP (Linear Program) as SDP:

- If A_i and B are diagonal \Rightarrow so is $B - \sum_{i=1}^m x_i A_i$.
- So it is psd iff diagonal elements are nonnegative.
- So LP can be modeled as SDP.

Why is SDP important:
 $LP \subseteq SDP \subseteq \text{Convex Optimization}$

LP (Linear Program) as SDP:

- If A_i and B are diagonal \Rightarrow so is $B - \sum_{i=1}^m x_i A_i$.
- So it is psd iff diagonal elements are nonnegative.
- So LP can be modeled as SDP.

SDP is a convex problem:

- Feasible set is convex, since set of psd matrices is.

Why is SDP important: applications in

- 0–1 Integer programming.
- Approx algorithms
- Chemical engineering
- Chemistry
- Coding theory
- Control theory
- Combinatorial opt
- Discrete geometry
- Eigenvalue optimization
- Facility planning
- Finance
- Geometric optimization
- Global optimization
- Graph visualization
- Inventory theory
- Machine learning
- Matrix analysis
- PDEs
- Probability theory
- Robust optimization
- Signal processing
- Statistics
- Structural optimization

Why is SDP important: beautiful theory in

- Duality
- Interior point methods
- Geometry

...and many interesting glitches

- Interior point methods do not work as well as in LP.
- Nor does duality theory.

SDP in a different shape

$$\inf_Y B \bullet Y$$

$$s.t. Y \succeq 0$$

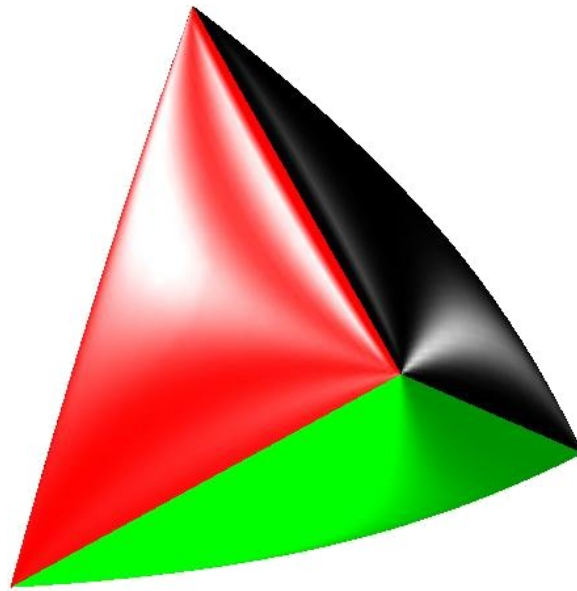
$$A_i \bullet Y = c_i \quad (i = 1, \dots, m).$$

Here

- A_i, B are symmetric matrices, $c \in \mathbb{R}^m$.
- $A \bullet B = \sum_{i,j} a_{ij} b_{ij}$
- Example: $\{Y \succeq 0 \mid y_{ii} = 1\}$ the set of correlation matrices.

3 by 3 correlation matrices

The set $\{ (x, y, z) \mid \begin{pmatrix} 1 & x & y \\ x & 1 & z \\ y & z & 1 \end{pmatrix} \succeq 0 \}$



SDP duality

The primal-dual pair of SDPs:

$$\begin{array}{ll} \sup_x c^T x & \inf_Y B \bullet Y \\ \text{s.t. } \sum_{i=1}^m x_i A_i \preceq B & Y \succeq 0 \\ & A_i \bullet Y = c_i \quad (i = 1, \dots, m). \end{array}$$

Easy: If x, Y are feasible $\Rightarrow c^T x \leq B \bullet Y$.

Ideally: $\exists x^*, Y^*$ such that $c^T x^* = B \bullet Y^*$.

SDP duality

The primal-dual pair of SDPs:

$$\begin{array}{ll} \sup_x c^T x & \inf_Y B \bullet Y \\ \text{s.t. } \sum_{i=1}^m x_i A_i \preceq B & Y \succeq 0 \\ & A_i \bullet Y = c_i \quad (i = 1, \dots, m). \end{array}$$

Easy: If x, Y are feasible $\Rightarrow c^T x \leq B \bullet Y$.

Ideally: $\exists x^*, Y^*$ such that $c^T x^* = B \bullet Y^*$.

But: SDPs, unlike LPs can be **pathological**: nonattainment, positive gaps.

Pathological SDPs often defeat SDP solvers.

Ben-Tal, Nemirovsky: “Is there something wrong with SDP duality?”

Pathology # 1: nonattainment in dual

Primal:

$$\begin{array}{ll} \sup 2x_1 & \Leftrightarrow \sup 2x_1 \\ \text{s.t. } x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} & \text{s.t. } \begin{pmatrix} 1 & -x_1 \\ -x_1 & 0 \end{pmatrix} \preceq 0 \end{array}$$

Pathology # 1: nonattainment in dual

Primal:

$$\begin{array}{ll} \sup 2x_1 & \Leftrightarrow \sup 2x_1 \\ \text{s.t. } x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} & \text{s.t. } \begin{pmatrix} 1 & -x_1 \\ -x_1 & 0 \end{pmatrix} \preceq 0 \end{array}$$

Only feasible x_1 is $x_1 = 0$.

Pathology # 1: nonattainment in dual

Primal:

$$\begin{aligned} \sup 2x_1 & \Leftrightarrow \sup 2x_1 \\ \text{s.t. } x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} & \text{s.t. } \begin{pmatrix} 1 & -x_1 \\ -x_1 & 0 \end{pmatrix} \preceq 0 \end{aligned}$$

Only feasible x_1 is $x_1 = 0$.

Dual: Dual variable is $Y \succeq 0$.

$$\begin{aligned} \inf y_{11} \\ \text{s.t. } \begin{pmatrix} y_{11} & 1 \\ 1 & y_{22} \end{pmatrix} \succeq 0 \end{aligned}$$

Pathology # 1: nonattainment in dual

Primal:

$$\begin{aligned} \sup 2x_1 \\ \text{s.t. } x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \end{aligned} \Leftrightarrow \begin{aligned} \sup 2x_1 \\ \text{s.t. } \begin{pmatrix} 1 & -x_1 \\ -x_1 & 0 \end{pmatrix} \preceq 0 \end{aligned}$$

Only feasible x_1 is $x_1 = 0$.

Dual: Dual variable is $Y \succeq 0$.

$$\begin{aligned} \inf y_{11} \\ \text{s.t. } \begin{pmatrix} y_{11} & 1 \\ 1 & y_{22} \end{pmatrix} \succeq 0 \end{aligned}$$

Unattained $\inf = 0$: $y_{11} > 0$ is feasible, but $y_{11} = 0$ is not.

Same story in pictures

Primal:

$$\sup 2x_1$$

$$s.t. -x_1^2 \geq 0$$

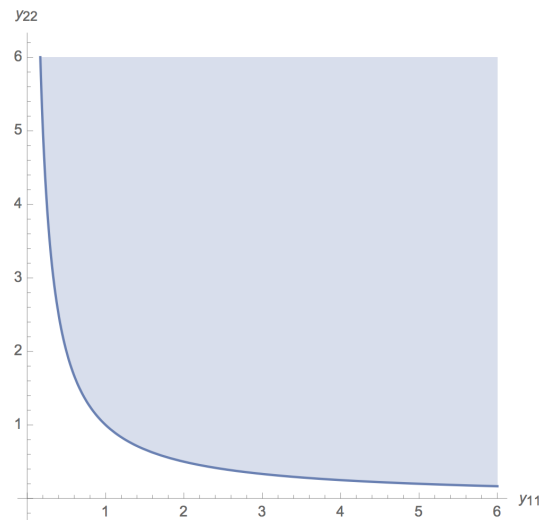
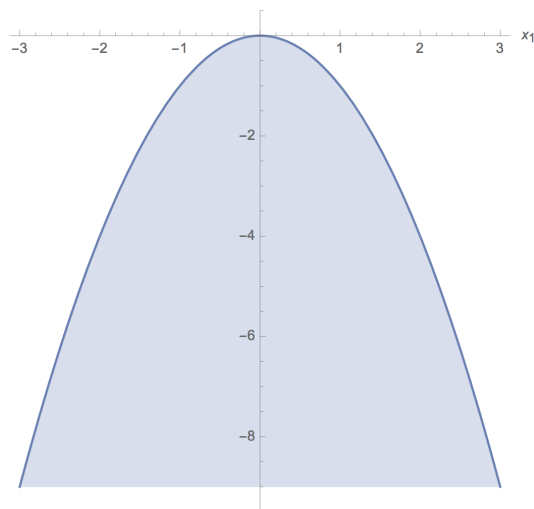
Dual:

$$\inf y_{11}$$

$$s.t. y_{11}y_{22} \geq 1$$

$$y_{11} \geq 0, y_{22} \geq 0.$$

Highest point on degenerate parabola vs. leftmost point on hyperbola



Pathology # 2: positive duality gap

Primal:

$$\begin{array}{l} \sup x_2 \\ \text{s.t. } x_1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \end{array}$$

Pathology # 2: positive duality gap

Primal:

$$\begin{array}{l} \sup x_2 \\ \text{s.t. } x_1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \end{array}$$

Only feasible x_2 is $x_2 = 0$.

Pathology # 2: positive duality gap

Primal:

$$\begin{array}{l} \sup x_2 \\ \text{s.t. } x_1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} \end{array}$$

Only feasible x_2 is $x_2 = 0$.

Dual value is **1**, and it is attained.

Bad behavior defined

We are curious about the semidefinite **system**

$$(P_{SD}) \sum_{i=1}^m x_i A_i \preceq B$$

Bad behavior defined

We are curious about the semidefinite **system**

$$(P_{SD}) \sum_{i=1}^m x_i A_i \preceq B$$

- We say that it is **badly behaved** if $\exists c$ such that

$$\sup\{c^T x \mid x \in (P_{SD})\} < +\infty$$

but the dual program has no solution with same value (i.e. dual does not attain, or positive gap).

- **Well behaved**, otherwise.
- A **slack** is $Z = B - \sum_i x_i A_i \succeq 0$.

Motivation

The systems

$$x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

and

$$x_1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

are both badly behaved.

Motivation

The systems

$$x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$$

and

$$x_1 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \sim \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

are both badly behaved.

Curious similarity – of these, and about 20 others in the literature

Why all bad SDPs look the same

- Semidefinite system:

$$(P_{SD}) \quad \sum_{i=1}^m x_i A_i \preceq B$$

- W.l.o.g. the max (rank) slack is

$$Z = \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}.$$

Why all bad SDPs look the same

- Semidefinite system:

$$(P_{SD}) \quad \sum_{i=1}^m x_i A_i \preceq B$$

- W.l.o.g. the max (rank) slack is

$$Z = \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}.$$

- Then (P_{SD}) badly behaved $\Leftrightarrow \exists V$ a lin. combination of the A_i as

$$V = \begin{pmatrix} \overbrace{V_{11}}^r & V_{12} \\ V_{12}^T & V_{22} \end{pmatrix}, \text{ where } V_{22} \succeq 0, \text{ R}(V_{12}^T) \not\subseteq \text{R}(V_{22}).$$

Why all bad SDPs look the same

- Semidefinite system:

$$(P_{SD}) \quad \sum_{i=1}^m x_i A_i \preceq B$$

- W.l.o.g. the max (rank) slack is

$$Z = \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}.$$

Then (P_{SD}) badly behaved $\Leftrightarrow \exists V$ a lin. combination of the A_i as

$$V = \begin{pmatrix} \overbrace{V_{11}}^r & V_{12} \\ V_{12}^T & V_{22} \end{pmatrix}, \text{ where } V_{22} \succeq 0, \mathbf{R}(V_{12}^T) \not\subseteq \mathbf{R}(V_{22}).$$

- Ex: $x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \not\preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$

Why all bad SDPs look the same

- Semidefinite system:

$$(P_{SD}) \quad \sum_{i=1}^m x_i A_i \preceq B$$

- W.l.o.g. the max (rank) slack is

$$Z = \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}.$$

Then (P_{SD}) badly behaved $\Leftrightarrow \exists V$ a lin. combination of the A_i as

$$V = \begin{pmatrix} \overbrace{V_{11}}^r & V_{12} \\ V_{12}^T & V_{22} \end{pmatrix}, \text{ where } V_{22} \succeq 0, \mathbf{R}(V_{12}^T) \not\subseteq \mathbf{R}(V_{22}).$$

- Ex: $x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \overbrace{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}}^Z$

Why all bad SDPs look the same

- Semidefinite system:

$$(P_{SD}) \quad \sum_{i=1}^m x_i A_i \preceq B$$

- W.l.o.g. the max (rank) slack is

$$Z = \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix}.$$

Then (P_{SD}) badly behaved $\Leftrightarrow \exists V$ a lin. combination of the A_i as

$$V = \begin{pmatrix} \overbrace{V_{11}}^r & V_{12} \\ V_{12}^T & V_{22} \end{pmatrix}, \text{ where } V_{22} \succeq 0, \mathbf{R}(V_{12}^T) \not\subseteq \mathbf{R}(V_{22}).$$

- Ex: $x_1 \overbrace{\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}}^V \preceq \overbrace{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}}^Z$

What is missing?

- Matrices Z, V prove that (P_{SD}) is badly behaved.
- But: they do not provide a “bad” c objective function
- Nor a poly time, or easy to verify proof of bad behavior

What is missing?

- Matrices Z, V prove that (P_{SD}) is badly behaved.
- But: they do not provide a “bad” c objective function
- Nor a poly time, or easy to verify proof of bad behavior
- Aside: how do we prove that $Ax = b$ is infeasible?

What is missing?

- Matrices Z, V prove that (P_{SD}) is badly behaved.
- But: they do not provide a “bad” c objective function
- Nor a poly time, or easy to verify proof of bad behavior
- Aside: how do we prove that $Ax = b$ is infeasible? \rightarrow row echelon form.

What is missing?

- Matrices Z, V prove that (P_{SD}) is badly behaved.
- But: they do not provide a “bad” c objective function
- Nor a poly time, or easy to verify proof of bad behavior
- Aside: how do we prove that $Ax = b$ is infeasible? \rightarrow row echelon form.
- We will borrow ideas from the row echelon form.

Reformulations of

$$(PSD) \sum_{i=1}^m x_i A_i \preceq B$$

are obtained by a sequence of:

- Apply a rotation $V^T(\cdot)V$ to all matrices, where V is invertible.
- $B \leftarrow B + \sum_{i=1}^m \mu_i A_i$
- $A_i \leftarrow \sum_{j=1}^m \lambda_j A_j$ where $\lambda_i \neq 0$
- Exchange A_i and A_j .

Reformulations of

$$(PSD) \sum_{i=1}^m x_i A_i \preceq B$$

are obtained by a sequence of:

- Apply a rotation $V^T(\cdot)V$ to all matrices, where V is invertible.
- $B \leftarrow B + \sum_{i=1}^m \mu_i A_i$
- $A_i \leftarrow \sum_{j=1}^m \lambda_j A_j$ where $\lambda_i \neq 0$
- Exchange A_i and A_j .

Mostly: just elementary row operations done on (D) . E.g. exchange constraints

$$A_i \bullet Y = c_i \text{ and } A_j \bullet Y = c_j$$

Theorem: (P_{SD}) is badly behaved \Leftrightarrow it has a reformulation:

$$(P_{SD,bad}) \quad \sum_{i=1}^k x_i \begin{pmatrix} F_i & 0 \\ 0 & 0 \end{pmatrix} + \sum_{i=k+1}^m x_i \begin{pmatrix} F_i & G_i \\ G_i^T & H_i \end{pmatrix} \preceq \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix} = Z,$$

where

- 1) Z is max slack; 2) $\begin{pmatrix} G_i \\ H_i \end{pmatrix}$ lin. indep. 3) $H_m \succeq 0$

Theorem: (P_{SD}) is badly behaved \Leftrightarrow it has a reformulation:

$$(P_{SD,bad}) \quad \sum_{i=1}^k x_i \begin{pmatrix} F_i & 0 \\ 0 & 0 \end{pmatrix} + \sum_{i=k+1}^m x_i \begin{pmatrix} F_i & G_i \\ G_i^T & H_i \end{pmatrix} \preceq \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix} = Z,$$

where

1) Z is max slack; 2) $\begin{pmatrix} G_i \\ H_i \end{pmatrix}$ lin. indep. 3) $H_m \succeq 0$

How to get there? Block Gaussian elimination!

$$\begin{pmatrix} \text{vec } A_1 \\ \vdots \\ \text{vec } A_m \end{pmatrix} \rightarrow \begin{pmatrix} \overbrace{\times}^{F_i} & \overbrace{\times}^{(G_i, H_i)} \\ \times & 0 \\ \times & \times \end{pmatrix}$$

Theorem: (P_{SD}) is badly behaved \Leftrightarrow it has a reformulation:

$$(P_{SD,bad}) \quad \sum_{i=1}^k x_i \begin{pmatrix} F_i & 0 \\ 0 & 0 \end{pmatrix} + \sum_{i=k+1}^m x_i \begin{pmatrix} F_i & G_i \\ G_i^T & H_i \end{pmatrix} \preceq \begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix} = Z,$$

where

1) Z is max slack; 2) $\begin{pmatrix} G_i \\ H_i \end{pmatrix}$ lin. indep. 3) $H_m \succeq 0$

Proof that $(P_{SD,bad})$ is badly behaved:

$$\begin{aligned} x \text{ feasible} &\Rightarrow x_{k+1} = \dots = x_m = 0 \\ &\Rightarrow \sup -x_m = 0 \end{aligned}$$

But: no dual soln with value 0

Example: before and after

$$x_1 \begin{pmatrix} 6 & 10 \\ 10 & 16 \end{pmatrix} \sim \begin{pmatrix} 19 & 32 \\ 32 & 52 \end{pmatrix}$$

is badly behaved, but how do we tell?

Example: before and after

$$x_1 \begin{pmatrix} 6 & 10 \\ 10 & 16 \end{pmatrix} \preceq \begin{pmatrix} 19 & 32 \\ 32 & 52 \end{pmatrix}$$

is badly behaved, but how do we tell?

After reformulation:

$$x_1 \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \preceq \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix},$$

which is trivially badly behaved.

Large example: before reformulation

$$\begin{aligned}
 & \mathbf{x}_1 \begin{pmatrix} 54 & 46 & 50 & 4 \\ 46 & -38 & 87 & -106 \\ 50 & 87 & -60 & 296 \\ 4 & -106 & 296 & -368 \end{pmatrix} + \mathbf{x}_2 \begin{pmatrix} 110 & 91 & 105 & -6 \\ 91 & -72 & 171 & -210 \\ 105 & 171 & -72 & 528 \\ -6 & -210 & 528 & -672 \end{pmatrix} + \mathbf{x}_3 \begin{pmatrix} 42 & 35 & 40 & 0 \\ 35 & -28 & 67 & -82 \\ 40 & 67 & -36 & 216 \\ 0 & -82 & 216 & -270 \end{pmatrix} \\
 & \qquad \qquad \qquad + \mathbf{x}_4 \begin{pmatrix} 36 & 30 & 35 & -2 \\ 30 & -24 & 57 & -70 \\ 35 & 57 & -24 & 176 \\ -2 & -70 & 176 & -224 \end{pmatrix} \preceq \begin{pmatrix} 389 & 323 & 370 & -12 \\ 323 & -257 & 610 & -748 \\ 370 & 610 & -288 & 1920 \\ -12 & -748 & 1920 & -2430 \end{pmatrix}
 \end{aligned}$$

Hard to tell if well or badly behaved

Large example: after reformulation

$$\begin{aligned}
 & x_1 \left(\begin{array}{cc|cc} 0 & 1 & 0 & 0 \\ 1 & -2 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) + x_2 \left(\begin{array}{cc|cc} 2 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) + x_3 \left(\begin{array}{cc|cc} 0 & 0 & 2 & 1 \\ 0 & 0 & 3 & -1 \\ \hline 2 & 3 & 0 & 2 \\ 1 & -1 & 2 & 0 \end{array} \right) \\
 & + x_4 \left(\begin{array}{cc|cc} 0 & 0 & 3 & -1 \\ 0 & 0 & 2 & -1 \\ \hline 3 & 2 & 4 & 0 \\ -1 & -1 & 0 & 0 \end{array} \right) \quad | \quad \left(\begin{array}{cc|cc} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ \hline 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right)
 \end{aligned}$$

As before: $x_3 = x_4 = 0 \Rightarrow \sup -x_4 = 0$

But: no dual solution with value 0

Corollaries:

- Similar reformulation for well-behaved systems.

Corollaries:

- Similar reformulation for well-behaved systems.
- The question:
 Is (P_{SD}) well behaved?
 is in $NP \cap coNP$ in real number model of computing.

Corollaries:

- Similar reformulation for well-behaved systems.
- The question:
 Is (P_{SD}) well behaved?
 is in $NP \cap coNP$ in real number model of computing.
- Certificate: reformulation, and proof that Z is max rank slack.

Corollaries:

- Similar reformulation for well-behaved systems.
- The question:
 - Is (P_{SD}) well behaved?
 - is in $NP \cap coNP$ in real number model of computing.
- Certificate: reformulation, and proof that Z is max rank slack.

How about proving infeasibility?

This part is joint with Minghui Liu.

Semidefinite System (spectrahedron)

$$A_i \bullet X = b_i \quad (i = 1, \dots, m) \quad (P)$$

$$X \succeq 0$$

Semidefinite System (spectrahedron)

$$A_i \bullet X = b_i \quad (i = 1, \dots, m) \quad (P)$$

$$X \succeq 0$$

Here

- A_i are symmetric matrices.
- $A \bullet B = \sum_{i,j} a_{ij} b_{ij}$.

Semidefinite System (spectrahedron)

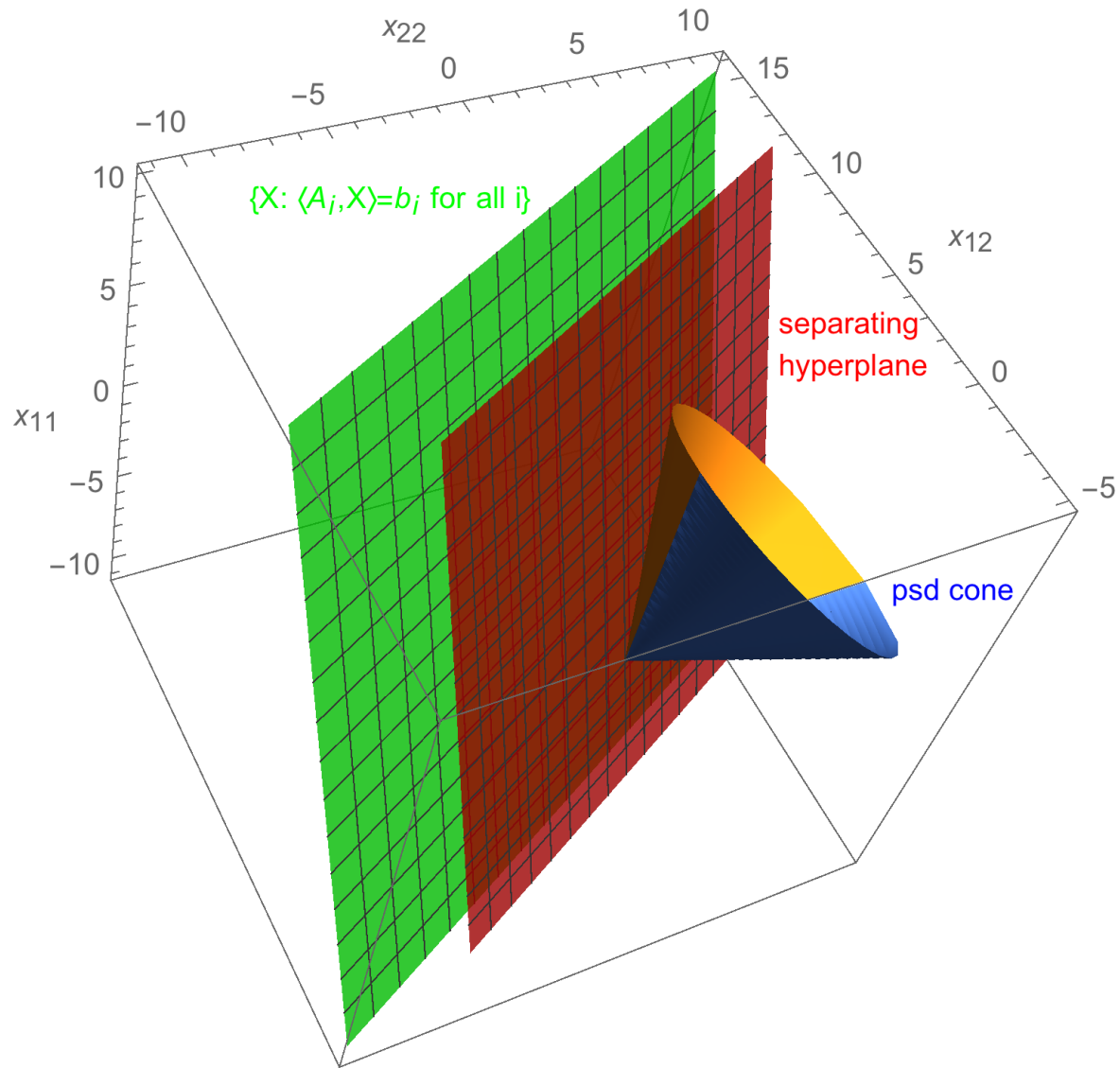
$$A_i \bullet X = b_i \quad (i = 1, \dots, m) \quad (P)$$

$$X \succeq 0$$

Here

- A_i are symmetric matrices.
- $A \bullet B = \sum_{i,j} a_{ij} b_{ij}$.
- **Thorny issue:** How to prove infeasibility?

Preferable way: by a separating hyperplane



Such a hyperplane may not exist!

On one hand

$$\begin{pmatrix} 0 & 1 \\ 1 & \times \end{pmatrix} \cap \text{psd cone} = \emptyset \rightarrow \text{infeasible SDP}$$

Such a hyperplane may not exist!

On one hand

$$\begin{pmatrix} 0 & 1 \\ 1 & \times \end{pmatrix} \cap \text{psd cone} = \emptyset \rightarrow \text{infeasible SDP}$$

On the other hand

$$\begin{pmatrix} \epsilon & 1 \\ 1 & 1/\epsilon \end{pmatrix} \succeq 0 \forall \epsilon > 0 \rightarrow \text{no separating hyperplane}$$

Such a hyperplane may not exist!

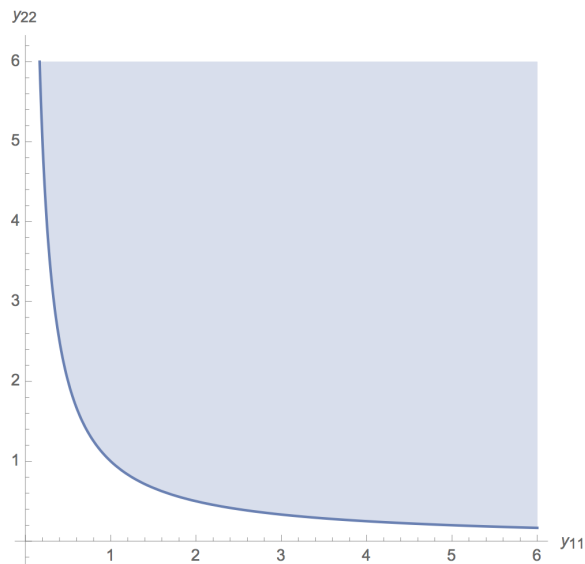
On one hand

$$\begin{pmatrix} 0 & 1 \\ 1 & \times \end{pmatrix} \cap \text{psd cone} = \emptyset \rightarrow \text{infeasible SDP}$$

On the other hand

$$\begin{pmatrix} \epsilon & 1 \\ 1 & 1/\epsilon \end{pmatrix} \succeq 0 \forall \epsilon > 0 \rightarrow \text{no separating hyperplane}$$

That hyperbola again ...



Literature: exact certificates of infeasibility

- Ramana 1995
- Ramana, Tuncel, Wolkowicz, 1997
- Klep, Schweighofer 2013
- Waki, Muramatsu 2013: variant of facial reduction of
- Borwein, Wolkowicz 1981
- These are more involved than a separating hyperplane

Ideas from Gaussian elimination

- **Goal:** Find an exact certificate of infeasibility that is “almost” as simple as a separating hyperplane.

Ideas from Gaussian elimination

- **Goal:** Find an exact certificate of infeasibility that is “almost” as simple as a separating hyperplane.
- How do we prove that $Ax = b$ is infeasible? \rightarrow row echelon form.

Ideas from Gaussian elimination

- **Goal:** Find an exact certificate of infeasibility that is “almost” as simple as a separating hyperplane.
- How do we prove that $Ax = b$ is infeasible? \rightarrow row echelon form.
- We will borrow ideas from the row echelon form.

Infeasible example, and proof of infeasibility

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \bullet X = 0$$
$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \bullet X = -1$$
$$X \succeq 0$$

Infeasible example, and proof of infeasibility

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \bullet X = 0$$
$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \bullet X = -1$$
$$X \succeq 0$$

- Suppose X feasible $\Rightarrow X_{11} = 0$
 $\Rightarrow X_{12} = X_{13} = 0$
 $\Rightarrow X_{22} = -1$

Infeasible example, and proof of infeasibility

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \bullet X = 0$$
$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \bullet X = -1$$
$$X \succeq 0$$

- Suppose X feasible $\Rightarrow X_{11} = 0$
 $\Rightarrow X_{12} = X_{13} = 0$
 $\Rightarrow X_{22} = -1$
- **Main idea:** We will find such a structure in every infeasible semidefinite system.

Reformulation

$$\begin{aligned} A_i \bullet X &= b_i \quad (i = 1, \dots, m) \\ X &\succeq 0 \end{aligned} \tag{P}$$

- We obtain a reformulation of (P) by a sequence of the following:
 - (1) Elementary row operations on the equations.
 - (2) $A_i \leftarrow V^T A_i V$ ($i = 1, \dots, m$), where V is invertible.
- (1) is inherited from Gaussian elimination.

Reformulation

$$\begin{aligned} A_i \bullet X &= b_i \quad (i = 1, \dots, m) \\ X &\succeq 0 \end{aligned} \tag{P}$$

- We obtain a reformulation of (P) by a sequence of the following:
 - (1) Elementary row operations on the equations.
 - (2) $A_i \leftarrow V^T A_i V$ ($i = 1, \dots, m$), where V is invertible.
- (1) is inherited from Gaussian elimination.
- **Fact:** Reformulations preserve (in)feasibility.

Some linear algebra

$$\begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix} \bullet X = 0, X \succeq 0 \Rightarrow ?$$

Some linear algebra

$$\begin{pmatrix} I_r & 0 \\ 0 & 0 \end{pmatrix} \bullet X = 0, X \succeq 0 \Rightarrow X = \begin{pmatrix} 0_r & 0 \\ 0 & X_{22} \end{pmatrix}, X_{22} \succeq 0.$$

Theorem: (P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 && (\text{P}_{\text{ref}}) \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$ the A'_i look like

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times}^{n-r_1-\dots-r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_1, \dots, r_{k+1} \geq 0$.

Theorem: (P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}
 \tag{P}_{\text{ref}}$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$ the A'_i look like

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times \times \dots \times}^{r_1 + \dots + r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times \times \dots \times}^{n-r_1 - \dots - r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_1, \dots, r_{k+1} \geq 0$.

Proof of “ \Leftarrow ” :

Theorem: (P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}
 \tag{P_{ref}}$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$ the A'_i look like

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times}^{n-r_1-\dots-r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_1, \dots, r_{k+1} \geq 0$.

Proof of “ \Leftarrow ” : Suppose that X feasible in (P_{ref})

Theorem: (P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 \quad (P_{\text{ref}}) \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$ the A'_i look like

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times}^{n-r_1-\dots-r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_1, \dots, r_{k+1} \geq 0$.

Proof of “ \Leftarrow ” : Suppose that X feasible in (P_{ref})
 \Rightarrow first r_1 rows of X are 0

Theorem: (P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 \quad (\text{P}_{\text{ref}}) \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$ the A'_i look like

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times}^{n-r_1-\dots-r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_1, \dots, r_{k+1} \geq 0$.

Proof of “ \Leftarrow ” : Suppose that X feasible in (P_{ref})

\Rightarrow first r_1 rows of X are 0

...

\Rightarrow first $r_1 + \dots + r_k$ rows of X are 0

Theorem: (P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 \quad (\text{P}_{\text{ref}}) \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$ the A'_i look like

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times \times \dots \times}^{r_1 + \dots + r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times \times \dots \times}^{n-r_1 - \dots - r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_1, \dots, r_{k+1} \geq 0$.

Proof of “ \Leftarrow ” : Suppose that X feasible in (P_{ref})

\Rightarrow first r_1 rows of X are 0

...

\Rightarrow first $r_1 + \dots + r_k$ rows of X are 0

$\Rightarrow A'_{k+1} \bullet X \geq 0$

Back to the Example

- Back to the example:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \bullet X = 0$$
$$\begin{pmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{pmatrix} \bullet X = -1$$
$$X \succ 0$$

Back to the Example

- Back to the example:

$$\begin{array}{c} \underbrace{\left(\begin{array}{ccc} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right)}_{A'_1} \\ \underbrace{\left(\begin{array}{ccc} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{array} \right)}_{A'_2} \end{array} \quad \begin{array}{l} \bullet X = 0 \\ \bullet X = -1 \end{array}$$

$$X \supseteq 0$$

Proof outline

- Based on simplified facial reduction algorithm: construct the A'_i one by one.
- “Difficult” direction is about 1.5 pages.
- Alternative: adapt a traditional facial reduction algorithm, the closest one is by Waki and Muramatsu.

Is this just theory?

- We cannot construct the reformulations in poly time :(
- To do so, we would need to solve SDPs exactly.
- However...

Application 1: simple proof that SDP feasibility is
in $NP \cap coNP$ in real number model

- Proof of NP : show feasible X .

Application 1: simple proof that SDP feasibility is
in $NP \cap coNP$ in real number model

- Proof of **NP**: show feasible X .
- Proof of **co-NP**: reformulation and how we got it:
 - $V \in \mathbb{R}^{n \times n}$ to encode all similarity transformations.
 - $T \in \mathbb{R}^{m \times m}$ to encode elementary row ops.

Application 2: generating infeasible SDPs

(P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 && (\text{P}_{\text{ref}}) \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$ the A'_i look like

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times}^{n-r_1-\dots-r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_1, \dots, r_{k+1} \geq 0$.

Application 2: generating infeasible SDPs

(P) infeasible \Leftrightarrow it has a reformulation

$$\begin{aligned}
 A'_i \bullet X &= 0 \quad (i = 1, \dots, k) \\
 A'_{k+1} \bullet X &= -1 && (\mathbf{P}_{\text{ref}}) \\
 &\vdots \\
 X &\succeq 0
 \end{aligned}$$

where $k \geq 0$, and for $i = 1, \dots, k + 1$ the A'_i look like

$$A'_1 = \begin{pmatrix} \overbrace{I}^{r_1} & \overbrace{0}^{n-r_1} \\ 0 & 0 \end{pmatrix}, \quad A'_i = \begin{pmatrix} \overbrace{\times}^{r_1+\dots+r_{i-1}} & \overbrace{\times}^{r_i} & \overbrace{\times}^{n-r_1-\dots-r_i} \\ \times & I & 0 \\ \times & 0 & 0 \end{pmatrix}$$

with $r_1, \dots, r_{k+1} \geq 0$.

- Using this result, we can generate **all** infeasible SDP problems, as:
 - (1) Generate a system like $(\mathbf{P}_{\text{ref}})$.
 - (2) Reformulate it.

Application 2: generating infeasible SDPs

- We can generate challenging instances!
- Problem library by **Liu-P** 2016: infeasible and weakly infeasible SDPs

Application 2: generating infeasible SDPs

- We can generate challenging instances!
- Problem library by **Liu-P 2016**: infeasible and weakly infeasible SDPs
- As to solving them: Douglas-Rachford splitting of **Liu-Ryu-Yin 2017**;
- Homotopy method of **Hauenstein,Liddell, Zhang 2018**

Application 3: recognizing infeasibility in practice

- Sometimes we do not even have to reformulate an SDP to find the trivial structure that proves infeasibility ...or to reduce the SDP.
- **Zhu-P-Tran-Dinh** Sieve-SDP preprocessor

Application 3: recognizing infeasibility in practice

- Sometimes we do not even have to reformulate an SDP to find the trivial structure that proves infeasibility ...or to reduce the SDP.
- **Zhu-P-Tran-Dinh** Sieve-SDP preprocessor
- Before and after picture of an SDP

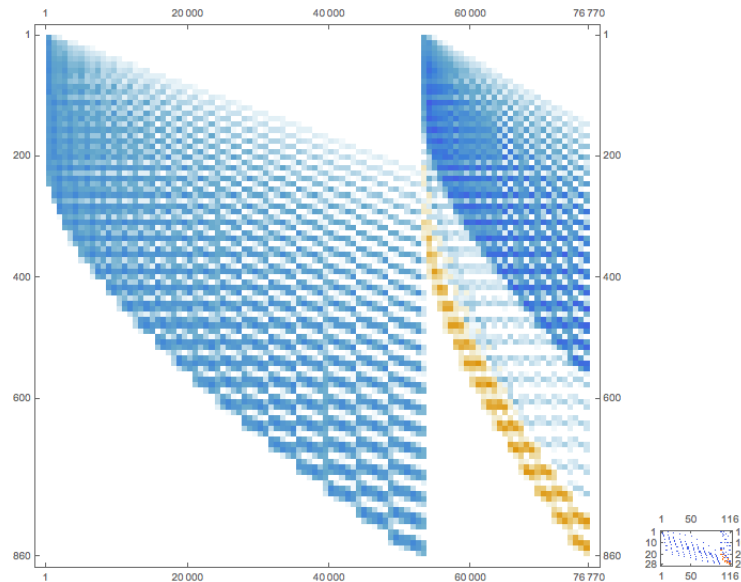


Figure 1: Instance “ex4.2_order20”: size and sparsity before and after preprocessing

Conclusion

- **Pathologies in duality:** well- and badly behaved semidefinite (feasible) systems.
- Combinatorial type characterizations.
- **Reformulations** to easily recognize good and bad behavior
→ $NP \cap co - NP$ certificates.

Conclusion

- **Pathologies in duality:** well- and badly behaved semidefinite (feasible) systems.
- Combinatorial type characterizations.
- **Reformulations** to easily recognize good and bad behavior
→ $NP \cap co - NP$ certificates.
- Exact, simple **certificate of infeasibility** of a semidefinite system based on elementary reformulation.
- Algorithm to systematically generate **all** infeasible SDPs.
- Other application: preprocessing by Sieve-SDP.

Papers

- **P:** Bad semidefinite programs: they all look the same, **2010–SIOPT 2017**
- **Liu–P:** Exact duality in semidefinite programming based on elementary reformulations, **SIOPT 2015**
- **Liu–P:** Exact duals and short certificates fo infeasibility and weak infeasibility in conic linear programming, **Math. Programming 2017.**

Papers

- **P:** Bad semidefinite programs: they all look the same, **2010–SIOPT 2017**
- **Liu–P:** Exact duality in semidefinite programming based on elementary reformulations, **SIOPT 2015**
- **Liu–P:** Exact duals and short certificates for infeasibility and weak infeasibility in conic linear programming, **Math. Programming 2017.**
- **P:** Characterizing bad semidefinite programs: normal forms and short proofs
SIAM Review, to appear
- **Zhu–P–Tran-Dinh:** Sieve-SDP: a simple algorithm to preprocess semidefinite programs
Mathematical Programming Computation, 2019
- **P:** On positive duality gaps in semidefinite programming, **2018**

Thank you!